

Country	Year	Population (millions)	Urban population (millions)	Urban population (%)	Population density (per sq km)	Urban population density (per sq km)	Population growth rate (%)	Urban population growth rate (%)	Population growth rate (%)	Urban population growth rate (%)	Population growth rate (%)	Urban population growth rate (%)
Algeria	1980	10.0	4.0	40.0	100.0	250.0	1.5	2.5	1.5	2.5	1.5	2.5
Algeria	1985	10.5	4.5	42.9	105.0	262.5	1.8	3.0	1.8	3.0	1.8	3.0
Algeria	1990	11.0	5.0	45.5	110.0	275.0	2.0	3.5	2.0	3.5	2.0	3.5
Algeria	1995	11.5	5.5	47.8	115.0	287.5	2.2	4.0	2.2	4.0	2.2	4.0
Algeria	2000	12.0	6.0	50.0	120.0	300.0	2.5	4.5	2.5	4.5	2.5	4.5
Algeria	2005	12.5	6.5	52.0	125.0	312.5	2.8	5.0	2.8	5.0	2.8	5.0
Algeria	2010	13.0	7.0	53.8	130.0	325.0	3.0	5.5	3.0	5.5	3.0	5.5
Algeria	2015	13.5	7.5	55.6	135.0	337.5	3.2	6.0	3.2	6.0	3.2	6.0
Algeria	2020	14.0	8.0	57.1	140.0	350.0	3.5	6.5	3.5	6.5	3.5	6.5
Algeria	2025	14.5	8.5	58.6	145.0	362.5	3.8	7.0	3.8	7.0	3.8	7.0
Algeria	2030	15.0	9.0	60.0	150.0	375.0	4.0	7.5	4.0	7.5	4.0	7.5
Algeria	2035	15.5	9.5	61.3	155.0	387.5	4.2	8.0	4.2	8.0	4.2	8.0
Algeria	2040	16.0	10.0	62.5	160.0	400.0	4.5	8.5	4.5	8.5	4.5	8.5
Algeria	2045	16.5	10.5	63.6	165.0	412.5	4.8	9.0	4.8	9.0	4.8	9.0
Algeria	2050	17.0	11.0	64.7	170.0	425.0	5.0	9.5	5.0	9.5	5.0	9.5
Algeria	2055	17.5	11.5	65.7	175.0	437.5	5.2	10.0	5.2	10.0	5.2	10.0
Algeria	2060	18.0	12.0	66.7	180.0	450.0	5.5	10.5	5.5	10.5	5.5	10.5
Algeria	2065	18.5	12.5	67.6	185.0	462.5	5.8	11.0	5.8	11.0	5.8	11.0
Algeria	2070	19.0	13.0	68.4	190.0	475.0	6.0	11.5	6.0	11.5	6.0	11.5
Algeria	2075	19.5	13.5	69.2	195.0	487.5	6.2	12.0	6.2	12.0	6.2	12.0
Algeria	2080	20.0	14.0	70.0	200.0	500.0	6.5	12.5	6.5	12.5	6.5	12.5
Algeria	2085	20.5	14.5	70.7	205.0	512.5	6.8	13.0	6.8	13.0	6.8	13.0
Algeria	2090	21.0	15.0	71.4	210.0	525.0	7.0	13.5	7.0	13.5	7.0	13.5
Algeria	2095	21.5	15.5	72.1	215.0	537.5	7.2	14.0	7.2	14.0	7.2	14.0
Algeria	2100	22.0	16.0	72.7	220.0	550.0	7.5	14.5	7.5	14.5	7.5	14.5
Algeria	2105	22.5	16.5	73.3	225.0	562.5	7.8	15.0	7.8	15.0	7.8	15.0
Algeria	2110	23.0	17.0	73.9	230.0	575.0	8.0	15.5	8.0	15.5	8.0	15.5
Algeria	2115	23.5	17.5	74.5	235.0	587.5	8.2	16.0	8.2	16.0	8.2	16.0
Algeria	2120	24.0	18.0	75.0	240.0	600.0	8.5	16.5	8.5	16.5	8.5	16.5
Algeria	2125	24.5	18.5	75.5	245.0	612.5	8.8					

for

by

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Automated Coring Machine and Method of Coring Produce

by

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BACKGROUND OF THE INVENTION

Technical Field of the Invention

The present invention relates to a high volume coring machine. More particularly, the present invention relates to an automated high volume produce coring machine which receives produce, feeds the produce to a coring station, and removes the core and skin of the produce before a subsequent cycle for another produce.

SUMMARY OF THE INVENTION

It is an object of the present invention to provide a produce coring machine.

It is a further objective of this invention to provide an automated produce coring machine.

It is yet an even further objective of the present invention to provide an automated high volume produce coring machine.

It is still an even further objective of this invention to provide an automated coring machine, comprising a frame having a feed area and a lifting device, a coring station mounted to the

frame and receiving the lifting device and, a programmable controller in electric communication with the lifting device and the coring station. The programmable controller is preferably a PLC fixedly attached to the frame and the lifting device

5 comprises an arcuate scoop having a feed area gate depending from the scoop. The automated coring machine scoop further comprises a switch in electrical communication with the programmable controller and the lifting device further comprises a fluid cylinder operably connected to the arcuate scoop. The fluid

10 cylinder of the lifting device further comprises an upper and a lower limit switch in electronic communication with the programmable controller.

The automated coring machine further comprises at least one blade spaced between the scoop and the coring station, the

15 blade being positionally adjustable.

The coring station further comprises a first fluid cylinder having a push plate mounted on a piston of the first fluid cylinder and the first fluid cylinder having limit switches in electrical communication with the programmable controller.

20 The automated coring machine further comprising a centering mechanism aligned with the push plate and spaced between the push plate and a circular blade, the circular blade being removably attached to said frame. The automated coring

machine further comprising a coring tube axially aligned with the circular blade.

The coring tube extends through a push donut mounted to the frame and being connected to a second fluid cylinder linearly aligned with the centering mechanism and the circular blade. The second fluid cylinder has limiting switches in electrical communication with the programmable controller.

A method of coring produce, comprising positioning the produce, cutting at least one flat surface in the produce, lifting the produce to a coring station, forcing the produce through a centering mechanism, removing an outer surface of the produce with a circular blade, impaling a produce with said coring tube, and removing the coring tube from the produce.

All of the above outlined objectives are to be understood as exemplary only and many more objectives of the invention may be gleaned from the disclosure herein. Therefore, no limiting interpretation of the objectives noted are to be understood without further reading of the entire specification and drawings included herewith.

#### BRIEF DESCRIPTION OF THE DRAWINGS

The aspects and advantages of the present invention will be better understood when the detailed description of the preferred

embodiment is taken in conjunction with the accompanying drawings, in which:

FIG. 1 shows a perspective view of the automated  
5 pineapple coring machine of the present invention;

FIG. 2 shows an upper perspective view of the lift device  
and coring station of the coring machine shown in Fig. 1;

FIG. 3 shows an end view of the coring blade used in the  
automated coring machine of Fig. 1;

10 FIG. 4A shows the lift device of the present invention in  
Fig. 1;

FIG. 4B shows the lift device of the present invention in  
the fully extended position;

15 FIG. 4C shows a produce moving through the coring station  
of the present invention of Fig. 1;

FIG. 4D shows a cored produce being removed from  
automated coring machine of the present invention; and,

FIG. 5 shows a wiring diagram between the programmable  
controller and the limit switches of the fluid cylinders.

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#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring to Figs. 1-5 an automated coring machine 10 is  
shown for coring produce such as pineapples. The coring machine

10 preferably has a lifting device 20, a coring station 40, and frame 60.

The frame 60 comprises parallel first and second members 62,64 and a first stand 66 and a second stand 68, which support  
5 the coring machine 10. Depending from frame 60 is a lifting device 20 for receiving produce from a feeding device such as a conveyor belt. The lifting device 20 inhibits bruising of the produce such as might happen if the produce is dropped into the coring station 40. The lifting device 20 comprises a fluid  
10 cylinder 22 having a piston 22a which extends and retracts between first and second positions but may normally be in a retracted position. The piston 22a is operably connected to a scoop 26 and has upper and lower limit switches 22b,22c. The fluid cylinder 22 may be operated by compressed air or hydraulic  
15 fluid. The scoop 26 may be made of plastic or preferably stainless steel. The lifting device 20 also comprises a feed area gate 24, preferably integral with the scoop 26 and depending from a side of the scoop 26 facing the feed area 30. The feed area gate 24 stops produce from entering the feed area 30 when the  
20 scoop 26 is in an upper position by extending through the feed area 30. The scoop 26 preferably has an arcuate shape and a switch 27 within the scoop 26 for signaling that a produce is

located therein. This signals the programmable controller 80 to start a coring machine 10 cycle. The switch 27 and upper and lower limit switches 22b, 22c are all in electrical communication with a programmable controller 80, preferably a programmable logic controller (PLC). The programmable controller 80 is preferably fixedly attached to the coring machine 10, but may be moved away from the coring machine 10 such as to a central room or the like.

At least one blade 28 is provided between the lifting device 20 and a coring station 40. The at least one blade 28, preferably two blades, are slidably attached to the frame 60 so that they may be centered with respect to the produce being cut. The at least one blade 28 is located within the path of travel of scoop 26. The at least one blade 28 may be slidably adjustable so to accept various sizes of produce for cutting.

Located above the lifting device 20 is a coring station 40. A first fluid cylinder 42 is mounted parallel to the frame 60, between the first frame member 62 and the second frame member 64. The first fluid cylinder 42 has a piston 42a, which is normally in a retracted position, and extended and retracted limit switches 42b, 42c. The limit switches 42b and 42c are in electrical communication with the programmable controller 80 and signal the controller 80 that the first fluid cylinder 42 is in

either a fully extended or retracted position. Attached to piston 42a is a push plate 46 which moves as piston 42 extends and retracts in a path parallel to frame 60. Located adjacent the push plate 46 is a centering mechanism 48 having a frusto-conical .  
5 shape with a first larger aperture 48a transitioning to a second smaller aperture 48b. The centering mechanism 48 is operably attached to the first and second frame members 62,64 by a plate 49 and is axially aligned with the first fluid cylinder 42 and push plate 46, within first and second frame members 62,64. The  
10 plate 49 is preferably made of stainless steel and has a hole therein where the centering mechanism 48 extends through and is affixed. The centering mechanism 48 is preferably made of plastic.

A circular blade 50 may be axially aligned with the second  
15 smaller aperture 48b of centering mechanism 48 and is removably attached to the first and second frame members 62,64 so that blades of various diameters may be used to remove the skin from various produce types. The circular blade 50 may, for example, be attached to first and second frame members 62,64 by using  
20 bolts 67 and wing nuts 65 or some other such easily removable mechanisms. The circular blade 50 may be made of metal, preferably stainless steel.



Adjacent the circular blade 50 is a coring tube 52 which is slidably mounted within the frame 60, axially aligned with the circular blade 50, and operably attached to a piston 58a of second fluid cylinder 58. Coring tube 52 is of a smaller diameter than circular blade 50 and may extend through a push donut 54, a donut plate 56, and when piston 58a is in a fully extended position, through the circular blade 50. Preferably piston 58a is connected to coring tube 52 by at least one linkage arm 57. As piston 58a moves from a retracted to an extended position, coring tube 52 slides through donut plate 56, push donut 54, and through circular blade 50. Second fluid cylinder 58 is fixedly attached to the frame 60 within the first and second frame members 62,64 and axially aligned with the centering mechanism 48 and circular blade 50.

Donut plate 56 is fixedly attached the first and second frame members 62,64. Push donut 54 is located on a side of the donut plate 56 adjacent the circular blade 50 and may be made of metal or stainless steel, but is preferably a plastic material.

Second fluid cylinder 58 may be operated by either compressed air or hydraulic fluid, and additionally has a first retracted limit switch 58b and a second extended limit switch 58c. The second fluid cylinder 58 may normally be in an extended position and the retracted and extended limit switches 58b, 58c

are in electrical communication with the programmable controller 80.

In use, a produce feeding conveyor belt may be attached to the frame 60 near in the feed area 30 to deliver produce, such as pineapple, to the coring machine 10. As shown in Figs. 4A-4D, the scoop 26 is initially in a lower position as piston 22a is retracted, allowing the pineapple to be positioned in the scoop 26. When the pineapple is positioned in the scoop 26, switch 27 activates the programmable controller 80 to begin the coring machine 10 cycle.

First, programmable controller 80 activates fluid cylinder 22 and the scoop 26 having a produce therein is raised between the at least one cutting blade 28. The, for example, two cutting blades 28 cut the ends of the pineapple extending past the scoop 26 sides creating two planar surfaces in the produce. The fluid cylinder 22 continues to raise the scoop 26 until the upper limit switch 22b is activated and the programmable controller 80 signals the fluid cylinder 22 to stop the piston 22a.

As the pineapple is held in an upper position within scoop 26, first fluid cylinder 42 is activated by the programmable controller 80 and begins extending push plate 46 and moving the pineapple through the coring station 40. The push plate 46

forces the pineapple through aperture 48a of centering mechanism 48. Push plate 46 continues extending and centering mechanism 48 properly aligns the pineapple before and during its entrance into the circular blade 50. As the push plate continues moving the pineapple through the centering mechanism 48 and through the circular blade 50, the outer skin of the pineapple is removed.

Since the second fluid cylinder 58 is normally in an extended position, coring tube 52 is adjacent the circular blade 50. As the first fluid cylinder 42 forces the pineapple through the circular blade 50, the center of the pineapple is impaled by the coring tube 52. Continued extension of the push plate 46 causes separation of the pineapple from its core as the core moves inside the coring tube 52 and the pineapple moves onto an outer surface of the coring tube 52. The extension of first fluid cylinder 42 stops as the extended limit switch 42b is reached. Push plate 46 is retracted until the retracted limit switch 42c is activated and first fluid cylinder 42 awaits the successive coring machine 10 cycle.

When the first fluid cylinder 42 retracted limit switch 42c is activated, a signal is sent to programmable controller 80. Programmable controller 80 then signals for second fluid cylinder 58 to begin retracting. With the pineapple riding on its outer surface, coring tube 52 begins retracting through push donut 54.

This continues as the pineapple contacts the push donut 54 and is extracted from the push donut 54. When the pineapple is fully removed from coring tube 52, it falls on a conveyor belt or some such means for moving produce. When the retracted limit switch  
5 58b is reached, a signal is sent to the programmable controller 80, and the second fluid cylinder 58 is extended to its normal position.

The invention may be embodied in various forms without departing from its spirit and essential characteristics. The  
10 described embodiments are not to be considered as restrictive.